

ДОДАТОК А
Програмна реалізація

preprocessing.py

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import os
import json
import gc
import cv2
import torch
import numpy as np
import pandas as pd
from facenet_pytorch import MTCNN

device = torch.device('cuda:0' if torch.cuda.is_available() else
'cpu')
facenet = MTCNN(image_size=200, margin=20, keep_all=True, factor=0.5,
device=device, post_process=False, select_largest=False).eval()

def get_videos_list_with_metadata(folder):
    files = os.listdir(folder)
    videos_names = [file for file in files if file[-3:] == 'mp4']
    metadata = pd.read_json(folder + 'metadata.json', orient='index')
    assert len(metadata) == len(videos_names)
    return videos_names, metadata

def extract_store_faces(filename, folder, destination_folder,
debug=False):
    max_faces_counter = dict()
    found_faces = 0
    total_frames = 0
    try:
        cap = cv2.VideoCapture(folder + filename)
        ret = True
        while cap.isOpened() and ret:
            try:
                ret, frame = cap.read()
                total_frames += 1
                if ret and frame is not None:
                    frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
                    face = facenet(frame,
                                save_path=destination_folder
                                +
filename[:-4] + '_' +
                                "{:04d}".format(total_frames) +
'.jpg')
                    if face is not None:
                        cnt = len(face)
                        found_faces += cnt
                        if cnt in max_faces_counter:
                            max_faces_counter[cnt] += 1
                        else:
                            max_faces_counter[cnt] = 1
            except Exception as e:
                print('Error: ', e)
                print('Frame_number: ', total_frames, '; file: ',
filename)
                if debug and total_frames > 10:
                    break
            gc.collect()
    except Exception as e:
        print('Error: ', e)
        print('; file: ', filename)

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finally:
    # get max_faces
    mf = np.array([[k, v] for k, v in max_faces_counter.items()])
    max_faces = int(mf[mf[:, 1].argmax(), 0])
    # prepare and save metadata
    metadata = {'max_faces': max_faces, 'found_faces':
found_faces, 'total_frames': total_frames}
    with open(destination_folder + filename[:-4] + '.json', 'w')
as fp:
        json.dump(metadata, fp)
        cap.release()

def process_folder(folder, destination_folder, start_index=0,
debug=False):
    files, metadata = get_videos_list_with_metadata(folder)
    i = 0
    for file in files:
        try:
            if start_index > i:
                continue
            i += 1
            extract_store_faces(file, folder, destination_folder,
debug=debug)

            if debug and i > 5:
                break
        except Exception as e:
            print("\n\n-----\nVideo
#{}, {}: {}".format(i, folder+file, e))

if __name__ == '__main__':
    dfolder = 'X:/DFDC_DATA/train/'
    path_to_data_folders = "X:/DFDC_DATA/"
    fmt = "dfdc_train_part_{}/"
    # process_folder(path_to_data_folders + fmt.format(1), dfolder)
    # folder1 = 'X:/DFDC_DATA/dfdc_train_part_2/'
    # fn1 = 'aejroilouc.mp4'
    # extract_faces(fn1, folder1, dfolder, debug=True)
    # for foldnum in range(2):
    #     process_folder(path_to_data_folders+fmt.format(foldnum),
dfolder, 845)

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model.py

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import os
import tqdm
import random
import cv2
import torch
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from dfdc.preprocessing import get_videos_list_with_metadata

random.seed(0)
np.random.seed(0)
torch.manual_seed(0)
torch.backends.cudnn.deterministic = True

def show_progress(train_loss_hist, valid_loss_hist, store=False):
    plt.close()
    plt.title('Train/validation loss history')

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plt.plot(train_loss_hist, label='train loss')
plt.plot(valid_loss_hist, label='validation loss')
plt.ylabel('Loss')
plt.xlabel('Epoch')
plt.legend()
if store:
    plt.savefig('iter_{}.png'.format(len(valid_loss_hist)),
dpi=300, bbox_inches='tight')
plt.show(block=False)

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class FakeDataset:
    def __init__(self, meta_folder, train_folder):
        self.train_folder = train_folder
        tmp = get_videos_list_with_metadata(meta_folder)
        self.raw_metadata = tmp[1]
        self._process_metadata()
        self._prepare_dataset()
        self._split_dataset()

    def _process_metadata(self):
        self.metadata = self.raw_metadata.reset_index().rename(columns={'index': 'filename'})
        self.metadata['filename'].map(lambda x: x[:-4], na_action='ignore')
        self.metadata['original'].map(lambda x: x[:-4], na_action='ignore')
        self.metadata['label'] = self.metadata['label'].map({'FAKE': 0., 'REAL': 1.})
        self.metadata = self.metadata.drop(columns=['split'])
        self.metadata.loc[self.metadata['original'].isna(),
'original'] = \
            self.metadata.loc[self.metadata['original'].isna(),
'filename']
        self.metadata = self.metadata.sort_values(['original'],
kind='mergesort')

    def _prepare_dataset(self):
        files_in_train_folder = os.listdir(self.train_folder)
        needed_files = [[file, file.split('_')] for file in
files_in_train_folder
                        if len(file.split('_')) == 2]
        filenames_from_meta = set(self.metadata['filename'])
        needed_files = [[file[0], file[1][0]] for file in
needed_files if file[1][0] in filenames_from_meta]
        self.X_filenames = pd.DataFrame(needed_files,
columns=['filename', 'filename_woe'])
        self.dataset = self.X_filenames.merge(self.metadata,
left_on='filename_woe', right_on='filename',
                                             how='inner',
validate='m:1', suffixes=('', '_meta'))
        self.dataset = self.dataset[['filename', 'label',
'original']] \
            .sort_values(['original'],
                        kind='mergesort',
ignore_index=True)

    def read_file(self, filename):
        try:
            frame = cv2.imread(self.train_folder + filename)
            frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
            return np.transpose(frame, (2, 0, 1))/256.
        except Exception as e:
            print('{}: {}'.format(filename, e))
            return None

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def _split_dataset(self):
    size = len(self.dataset)
    train_part = int(0.8*size)
    treshhold = self.dataset.iloc[train_part]['original']
    treshhold_index = self.dataset[self.dataset['original'] ==
treshhold].index[-1] + 1
    self.train = self.dataset.iloc[:treshhold_index]
    self.valid = self.dataset.iloc[treshhold_index:]
    self.train = self.train.reset_index(drop=True)
    self.valid = self.valid.reset_index(drop=True)

    self.valid['filename_w'] = self.valid['filename'].str[: -9]
    groups = self.valid.groupby('filename_w', as_index=False,
sort=False).groups
    ids = []
    for k, v in groups.items():
        # if (dataset.valid[dataset.metadata['filename'] ==
k] == 1.):
            idx_ = np.random.permutation(len(v))[:2]
            # else:
            ids.append(v[idx_].values)
    ids = np.stack(ids, axis=1).flatten()
    self.test = self.valid.iloc[ids]

class DeepFakeDetector(torch.nn.Module):
    def __init__(self):
        super(DeepFakeDetector, self).__init__()
        activation_function = torch.nn.ReLU()
        pooling_layer = torch.nn.MaxPool2d(kernel_size=2, stride=2)

        self.conv1_1 = torch.nn.Conv2d(
            in_channels=3, out_channels=8, kernel_size=3, padding=1)
        self.conv1_2 = torch.nn.Conv2d(
            in_channels=8, out_channels=16, kernel_size=3, padding=1)
        self.act1 = activation_function
        self.bn1 = torch.nn.BatchNorm2d(num_features=16)
        self.pool1 = pooling_layer

        self.conv2_1 = torch.nn.Conv2d(
            in_channels=16, out_channels=32, kernel_size=3,
padding=1)
        self.conv2_2 = torch.nn.Conv2d(
            in_channels=32, out_channels=32, kernel_size=3,
padding=1)
        self.act2 = activation_function
        self.bn2 = torch.nn.BatchNorm2d(num_features=32)
        self.pool2 = pooling_layer
        self.conv3 = torch.nn.Conv2d(
            in_channels=32, out_channels=32, kernel_size=3,
padding=1)

        self.act3 = activation_function
        self.pool3 = torch.nn.AdaptiveAvgPool2d(1)

        self.fc1 = torch.nn.Linear(32, 64)
        self.act4 = torch.nn.Tanh()

        self.fc2 = torch.nn.Linear(64, 1)

    def forward(self, x):

        x = self.conv1_2(self.conv1_1(x)) # 16 x 200 x 200
        x = self.act1(x)

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        x = self.bn1(x)
        x = self.pool1(x) # 16 x 100 x 100

        x = self.conv2_2(self.conv2_1(x)) # 32 x 100 x 100
        x = self.act2(x)
        x = self.bn2(x)
        x = self.pool2(x) # 32 x 50 x 50

        x = self.conv3(x)
        x = self.act3(x)
        x = self.pool3(x)
        x = x.view(x.size(0), x.size(1) * x.size(2) * x.size(3))

        x = self.fc1(x)
        x = self.act4(x)
        x = self.fc2(x)

    return x

def train(net, dataset, epoch_count=3):
    device = torch.device('cuda:0' if torch.cuda.is_available() else
'cpu')
    net = net.to(device)
    loss = torch.nn.BCEWithLogitsLoss()
    optimizer = torch.optim.Adam(net.parameters(), lr=1.0e-3)

    batch_size = 64
    test_batch_size = 64

    accumulated_loss = 0
    train_loss_history = []
    test_accuracy_history = []
    test_loss_history = []
    bp = 0
    examples = 0

    X_train = dataset.train['filename']
    y_train = dataset.train['label'].values

    X_test = dataset.test['filename']
    y_test = dataset.test['label'].values

    X_test = torch.stack([torch.tensor(dataset.read_file(filename))
for filename in X_test])
    y_test = torch.tensor([y_test]).transpose(1, 0)

    for epoch in range(epoch_count):
        order = np.random.permutation(len(X_train))
        for start_index in tqdm.tqdm(range(0, len(X_train),
batch_size)):
            optimizer.zero_grad()
            net.train()

            batch_indexes = order[start_index:start_index +
batch_size]

            X_batch = torch.stack(
                [torch.tensor(dataset.read_file(filename))
for filename in X_train[batch_indexes]].to(device,
dtype=torch.float)
            y_batch =
torch.tensor([y_train[batch_indexes]].transpose(1,
0)).to(device,

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dtype=torch.float)

        preds = net.forward(X_batch)

        loss_value = loss(preds, y_batch)
        loss_value.backward()
        optimizer.step()

        examples += len(y_batch)
        accumulated_loss +=
loss_value.data.cpu().item()*len(y_batch)

        del X_batch, y_batch, preds, loss_value
        torch.cuda.empty_cache()

        bp += 1
        if bp % 500 == 10:
            train_loss_history.append(accumulated_loss /
examples)

            accuracy = 0
            accumulated_loss = 0
            examples = 0
            for start_index2 in tqdm.tqdm(range(0, len(X_test),
test_batch_size)):
                net.eval()

                X_batch = X_test[start_index2: start_index2 +
test_batch_size].to(device, dtype=torch.float)
                y_batch = y_test[start_index2: start_index2 +
test_batch_size].to(device, dtype=torch.float)

                test_preds = net.forward(X_batch)

                loss_value = loss(test_preds, y_batch)

                examples += len(y_batch)
                accumulated_loss += loss_value.data.cpu().item()
* len(y_batch)

                accuracy +=
(torch.round(torch.nn.Sigmoid()(test_preds))
y_batch).float().sum().data.cpu().item()

                del X_batch, y_batch, test_preds, loss_value
                torch.cuda.empty_cache()

                test_loss_history.append(accumulated_loss/examples)
                test_accuracy_history.append(accuracy/examples)
                accumulated_loss = 0
                torch.save(net.state_dict(),
'model_iter_{}'.format(len(test_accuracy_history)))
                show_progress(train_loss_history, test_loss_history,
True)

                print('epoch: {}, accuracy: {}'.format(bp/500,
accuracy/examples))
                print('-----')
                return test_accuracy_history, test_loss_history

    if __name__ == '__main__':
        dataset = FakeDataset('X:/DFDC_DATA/dfdc_train_part_0/',
'X:/DFDC_DATA/train_data/train/')
        dfnet = DeepFakeDetector()
        train(dfnet, dataset)

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ДОДАТОК Б

Відомість аттестаційної роботи магістра

