

Додаток А

Код програми

base.py

```

from abc import ABC, abstractmethod
from typing import Any, Dict
from app.core.models import SensorTestResult
from app.core.logic import evaluate

class SensorAdapter(ABC):
    def __init__(self, cfg: Dict[str, Any]):
        self.cfg = cfg

    @abstractmethod
    async def _read(self) -> float:
        """Асинхронно зчитати сире числове значення."""
        ...

    async def test(self) -> SensorTestResult:
        try:
            value = await self._read()
            return evaluate(
                raw_value=value,
                mn=self.cfg["expect_min"],
                mx=self.cfg["expect_max"],
                sensor_id=self.cfg["id"],
            )
        except Exception as exc:
            return evaluate(
                raw_value=None,
                mn=0,
                mx=0,
                sensor_id=self.cfg["id"],
                error=str(exc),
            )

```

modbus.py

```

from abc import ABC, abstractmethod
from typing import Any, Dict
from app.core.models import SensorTestResult
from app.core.logic import evaluate

class SensorAdapter(ABC):
    def __init__(self, cfg: Dict[str, Any]):
        self.cfg = cfg

```

```

@abstractmethod
async def _read(self) -> float:
    """Асинхронно зчитати сире числове значення."""
    ...

async def test(self) -> SensorTestResult:
    try:
        value = await self._read()
        return evaluate(
            raw_value=value,
            mn=self.cfg["expect_min"],
            mx=self.cfg["expect_max"],
            sensor_id=self.cfg["id"],
        )
    except Exception as exc:
        return evaluate(
            raw_value=None,
            mn=0,
            mx=0,
            sensor_id=self.cfg["id"],
            error=str(exc),
        )

```

endpoints.py

```

from abc import ABC, abstractmethod
from typing import Any, Dict
from app.core.models import SensorTestResult
from app.core.logic import evaluate

class SensorAdapter(ABC):
    def __init__(self, cfg: Dict[str, Any]):
        self.cfg = cfg

    @abstractmethod
    async def _read(self) -> float:
        """Асинхронно зчитати сире числове значення."""
        ...

    async def test(self) -> SensorTestResult:
        try:
            value = await self._read()
            return evaluate(
                raw_value=value,
                mn=self.cfg["expect_min"],
                mx=self.cfg["expect_max"],
            )
        except Exception as exc:
            return evaluate(
                raw_value=None,
                mn=0,
                mx=0,
                error=str(exc),
            )

```

```

        sensor_id=self.cfg["id"],
    )
except Exception as exc:
    return evaluate(
        raw_value=None,
        mn=0,
        mx=0,
        sensor_id=self.cfg["id"],
        error=str(exc),
    )

```

logic.py

```

from datetime import datetime
from app.core.models import SensorTestResult

__all__ = ["evaluate"]

def evaluate(raw_value: float | None,
            mn: float,
            mx: float,
            sensor_id: str,
            error: str | None = None) -> SensorTestResult:
    status = raw_value is not None and mn <= raw_value <= mx and error
    is None
    return SensorTestResult(
        id=sensor_id,
        timestamp=datetime.utcnow(),
        value=raw_value,
        status=status,
        error=error,
    )

```

models.py

```

from datetime import datetime
from pydantic import BaseModel, Field

class SensorTestResult(BaseModel):
    id: str = Field(..., description="Унікальний ідентифікатор датчика")
    timestamp: datetime
    value: float | None
    status: bool
    error: str | None = None

```

settings.py

```

from functools import lru_cache
from pydantic_settings import BaseSettings, SettingsConfigDict

class Settings(BaseSettings):
    app_host: str = "0.0.0.0"
    app_port: int = 8000
    db_url: str = "sqlite:///results.db"
    poll_interval_sec: int = 30

    model_config = SettingsConfigDict(env_file=".env", extra="ignore")

@lru_cache
def get_settings() -> Settings:
    return Settings()

```

modbus_sim.py

```

"""
Modbus-TCP Simulator
"""

import threading
import time
from random import uniform

from pymodbus.datastore import (
    ModbusSparseDataBlock,
    ModbusSlaveContext,
    ModbusServerContext,
)

try:
    # старі версії pymodbus ≤3.5
    from pymodbus.server.sync import StartTcpServer # type: ignore
except (ModuleNotFoundError, ImportError):
    # нові pymodbus ≥3.9
    from pymodbus.server import StartTcpServer # type: ignore

class DynBlock(ModbusSparseDataBlock):
    def __init__(self, addr: int):
        super().__init__({addr: 0})
        self.addr = addr
        threading.Thread(target=self._gen, daemon=True).start()

    def _gen(self):
        while True:

```

```

        v = int(uniform(15.0, 30.0) * 10)
        self.setValues(self.addr, [v])
        print(f"[SIM] UPDATE addr={self.addr} <- {v}")
        time.sleep(5)

    def getValues(self, address, count=1):
        vals = super().getValues(address, count)
        print(f"[SIM] READ   addr={address} -> {vals}")
        return vals

def main() -> None:
    slave_ctx = ModbusSlaveContext(hr=DynBlock(100))
    ctx = ModbusServerContext(slaves={1: slave_ctx}, single=False)

    print("[SIM] Modbus-TCP listening on 0.0.0.0:5020 (Slave ID 1, Reg
100)")
    StartTcpServer(context=ctx, address=("0.0.0.0", 5020))

if __name__ == "__main__":
    main()

```

__init__.py

```

from fastapi import FastAPI
from app.api.endpoints import router

app = FastAPI(title="Sensor Checker")
app.include_router(router)

```

config.yaml

```

sensors:
  - id: temp_room_1
    proto: modbus
    host: ::1
    port: 5002
    unit: 1
    register: 100
    expect_min: 15.0
    expect_max: 30.0

```

Додаток Б
Демонстраційний матеріал

