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ABSTRACT

Master's thesis: 77 pages, 18 figures, 3 tables, 1 appendices, 23 sources.

IOT, INTERNET OF THINGS, GEOCONTEXT DATA, ANALYSIS,
DATA PROCESSING, INFORMATION SYSTEM.

The major goal of this thesis is analysis of models and methods of automated data processing in IoT.

A formal description of the model of the Danish for the end of the geocontext rozmitki Dano oT. The basic daily and structure of the Danish are described. Visited operations on these many. Directly put the victorious views of the operation for the main scenarios of work with geo-contextual data oT. The specificity of the model is described – the nullity is typical of the format of the dzherel itself, so it is the structure of geocontextual data. It is shown that a model for the content of the vimogs of the delivered assignment for the application analysis of the operation and installation of the IoT vimogs was introduced. The method of automated processing of geo-contextual data oT is described. The main stages of processing are described - rebuilding, individual, geo-contextual rozm tka, group geo-contextual rozm ka.

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1		IOT	11
1.1			11
1.2			14
1.2.1			14
1.2.2			16
1.2.3			20
1.3	-		21
1.4			23
1.5			24
1.5.1			25
1.5.2			27
1.5.3			28
1.6			28
1.7			31
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2.1.1			34
2.1.2			38
2.2			40
2.2.1			42
2.2.2			44
2.2.3			45

3	49
3.1	49
3.1.1	49
3.1.2	50
3.1.3	52
3.2	54
3.3	57
3.4	58
3.5	58
3.5.1	59
3.6.	61
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Analytics

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[36].

JSON, XML, CSV, RDF.

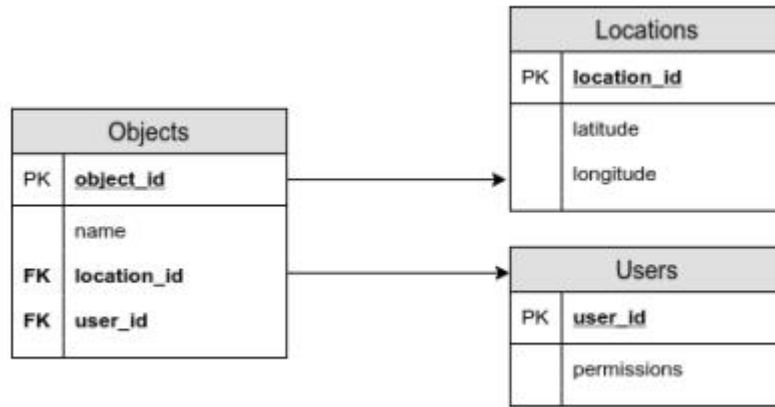
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Resource Description Framework (RDF).

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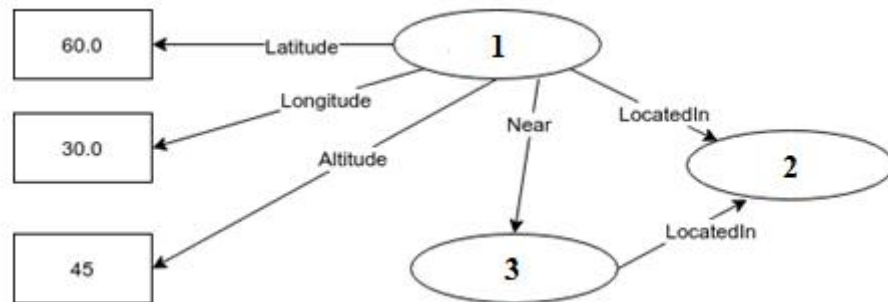
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RDFS.

CRUD,

RDF

MarkLogic, Jena, Virtuoso.



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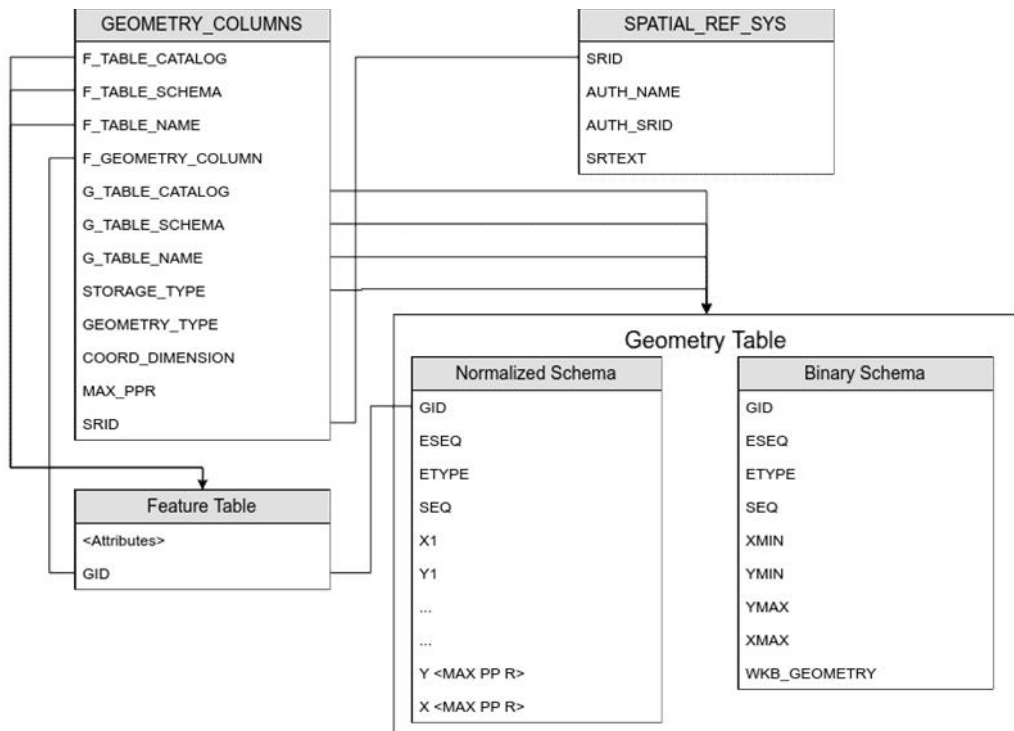
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OpenGeoConsortium,

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Geographic

Markup Language (GML) [52], XML-
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 XML- – GML- ,
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 , - . GML [55]
 (Feature) – , ,
 . (Geometry) – , ,
 , ,
 (Coordinate reference system),
 . (Topology) , ,
 . (Time) , .
 (Map presentation styling rules),
 . OGC
 . , :
 (Point), , .
 (Curve), ,
 . (Surface), ,
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 OGC :
 GML

GML Application Schema -

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 - CityGML,
 - ARML2.0,
 - GeoSciML,

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«Location-aware computing».

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(Data Lake).

(Data Warehouse)

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IBM [40]

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(Data Lake).

Apache Hadoop, Azure Data Lake [38], Amazon S3 [18].

) [95].

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1.6 –



1.7 –

1.2

$T_a(S), T_m(S), T_e(S)$
 S –
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1.2 –

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	$T_a(S) + T_m(S) < C, C > 0$	$T_a(S) + T_m(S) + T_e(S) < C, C > 0$
	$T_a(S) + T_m(S) < T$	$T_a(S) + T_m(S) + T_e(S) < T$
	$T_a(S) + T_m(S) \ll T_t$	$T_a(S) + T_m(S) + T_e(S) \ll T_t$

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2.1.1

$\langle id, description, location, datetime, channelid \rangle, p \in P$

$$p = \langle id, description, location, datetime, channelid \rangle, p \in P. \quad (2.1)$$

$\langle id, name, description \rangle, c \in C$

$$c = \langle id, name, description \rangle, c \in C, \quad (2.2)$$

,

channelid.

:

$$A = \{(a_1, \dots, a_m)\}, m > 0;$$

$$K = \{(\text{latitude}, \text{longitude}, \text{altitude})\} \subset \mathbb{R}^3. \quad (2.3)$$

, K – WGS-84 [13].
 Id, channelid –

$$id, channelid \in \mathbb{N} \quad (2.4)$$

Location – , (2.4):

$$location = \{l_1 .. l_m\}, li = \{li_1 .. li_n\}, li_j \in K, n, m \in \mathbb{N}. \quad (2.5)$$

li ,
 (m = 1),
 , (m > 1). location

Datetime – , ,
 , [14],

$$datetime \in . \quad (2.6)$$

Description –
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 « » « » , .

$$description = \{(ai, bi)\}, i \in a, b \in A., Name – . \quad (2.7)$$

$$name \in A. \quad (2.8)$$

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$$M: A \quad K. \tag{2.9}$$

(P C).

(BP),

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$$Fp: Bp \quad P, F : B . \tag{2.10}$$

$$f p (\text{location}): K \quad P, \tag{2.11}$$

$$f p (\text{datetime}): \mathbb{N} \rightarrow P, \tag{2.12}$$

$$f p (\text{id}): \mathbb{N} \rightarrow P, \tag{2.13}$$

$$f p (\text{description}): A \quad P, \tag{2.14}$$

datetime:

$$f_p(\text{id}): \text{findPointById}(\text{id}) = \{p \in P: \text{id} = (\text{id})\}, \quad (2.15)$$

$$f_p(\text{datetime}): \text{changePointDatetime}(\text{datetime}) = p, \quad (2.16)$$

$$p = \langle \text{id}, \text{description}, \text{location}, \text{datetime}, \text{channelid} \rangle, \quad (2.17)$$

$$p = \langle \text{id}, \text{description}, \text{location}, \text{datetime}, \text{channelid} \rangle, p, p \in P. \quad (2.18)$$

(latitude, longitude) r.

$$f_p(\text{location}): \text{findByDistance}(P, \text{latitude}, \text{longitude}, r) = \{P \in P \mid \forall l \in \text{location}: \text{dist}(l, (\text{latitude}, \text{longitude})) < r\}, \quad (2.19)$$

distance –

$$f_p(p): P \rightarrow P,$$

$$f_p(): P. \quad (2.20)$$

:

$$f_c(p): P \rightarrow C, f_c(\text{id}): \mathbb{N} \rightarrow C, f_c(\text{description}): A \rightarrow C. \quad (2.21)$$

:

$$f_c(p): \text{pointChannel}(p) = \{c \in C \mid p.\text{channelid} = c.\text{id}\} \quad (2.22)$$

$$f_c(\text{id}): \text{channelById}(\text{id}) = \{c \in C : \text{id} = (c.\text{id})\}, \quad (2.23)$$

$$f_c(\text{description}): \text{channelByDescription}(\text{description}) = \{C \in C \mid \text{description} = C.\text{description}\}. \quad (2.24)$$

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WGS-84

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name description,

channelid

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$$f_{11}(a): A \rightarrow P, f_{12}(a): C, a \in A \quad (2.25)$$

(f 21 (p))

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(f 22 (p))

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$$f_{21}(p): P \rightarrow P, p \in P \quad (2.26)$$

$$f_{22}(c_1, c_2): C \rightarrow C, c_2 \in C, c_1 \in C \quad (2.27)$$

$$f_{31}(c, S(p)): C \rightarrow P, S(p): P \rightarrow P, c \in C, \quad (2.28)$$

$$f_{32}(c, p): (C, P) \rightarrow P, c \in C, p \in P, f_{31}(c, S(p)) \quad (2.29)$$

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, $S(p)$ -

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, $f_{32}(c, p)$ - $S(p)$

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2.2.1

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Data: $\bar{A} = \{a_{ij}\}, i \in [1, n], j \in [1, m]$

Result: C, P

for $i=1; i \leq n; i++$ **do**

$n_c, d_c \leftarrow i$ -ый источник;

 создать c_i с названием n_c и описанием d_c ;

for $j=1; j \leq m; j++$ **do**

$n_p, d_p, t_p, l_p \leftarrow a_{ij}$;

 создать p_{ij} с атрибутами n_p, d_p, t_p, l_p ;

$P \leftarrow p_{ij}$ включить p_{ij} в c_i ;

end

end

C = $\{c_i\}$;

P = $\{p_{ij}\}$;

return C, P

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2.2.2

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(location) (description)

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Data:  $P, C_{match} \subset C$ 
Result:  $\bar{P}, \bar{C}$ 
for  $p \in P$  do
  |  $d_p = p.description;$ 
  |  $l_p = geocode(d_p);$ 
  |  $p.location = l_p$ 
end
for  $(c_i, c_k)$  in  $C_{match}$  do
  |  $создать \bar{c}_{ik};$ 
  | for  $j=1; j \leq m; j++$  do
  | |  $P_{sim} = find\_similar\_points(p_{ij}, c_k);$ 
  | |  $\bar{p} = merge\_attr(p_{ij}, P_{sim});$ 
  | |  $включить \bar{p}$  в  $\bar{c}_{ik};$ 
  | end
end
return  $\bar{P}, \bar{C}$ 

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Data: $P, C, C_{match} \subset C, S: C \rightarrow P$

Result: P, C

$c_s = \emptyset$;

for $c \in C$ **do**

```

| i = c.id;
|  $p_i = S(c)$ ;
| ВКЛЮЧИТЬ  $p_i$  В  $c_s$ ;

```

end

for c in C_{match} **do**

```

| i = c.id;
|  $\bar{p} = \text{get\_point}(c_s, i)$ ;
| for  $j=1; j \leq m; j++$  do
| |  $p_{ij} = \text{merge\_attr}(p_{ij}, \bar{p})$ ;
| end

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end

return P, C

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3.1

3.1.1

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«4 + 1», Open Group Architecture Framework,
ISO / IEC / IEEE 42010 . [23, 34]

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[34]

«Views and Beyond»,

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«Views and Beyond»,

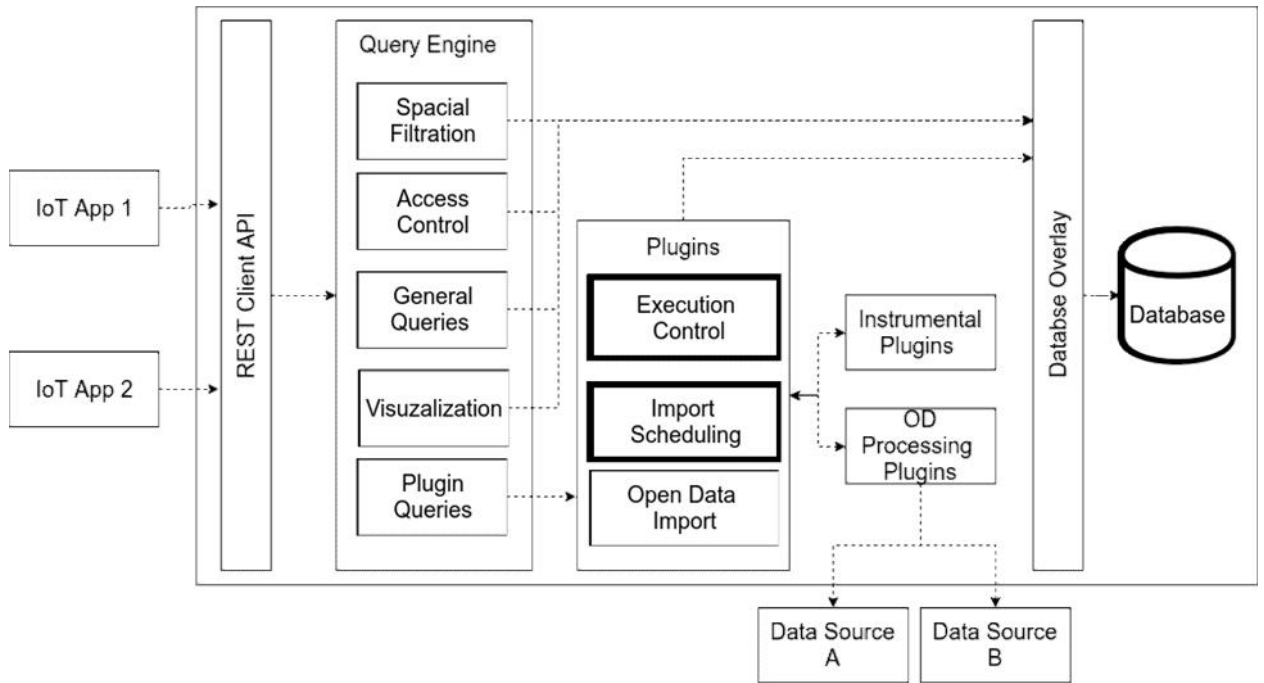
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3.1.2

3.1



3.1 –

REST [80] Client API,

[15, 74].

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Queries).

(General

Filtration).

(Spacial

(Plugin Queries).

(Visualization).

(Access Control).

REST Client API Web

Query

Engine.

(Database Overlay).

Plugins

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(Execution Control),

Import Sheduling),

(Open Data Import).

Plugins.

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(OD Import Plugins)

(Instrumental Plugins).

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Database Overlay

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(Database).

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Database, Import Sheduling Execution Control.

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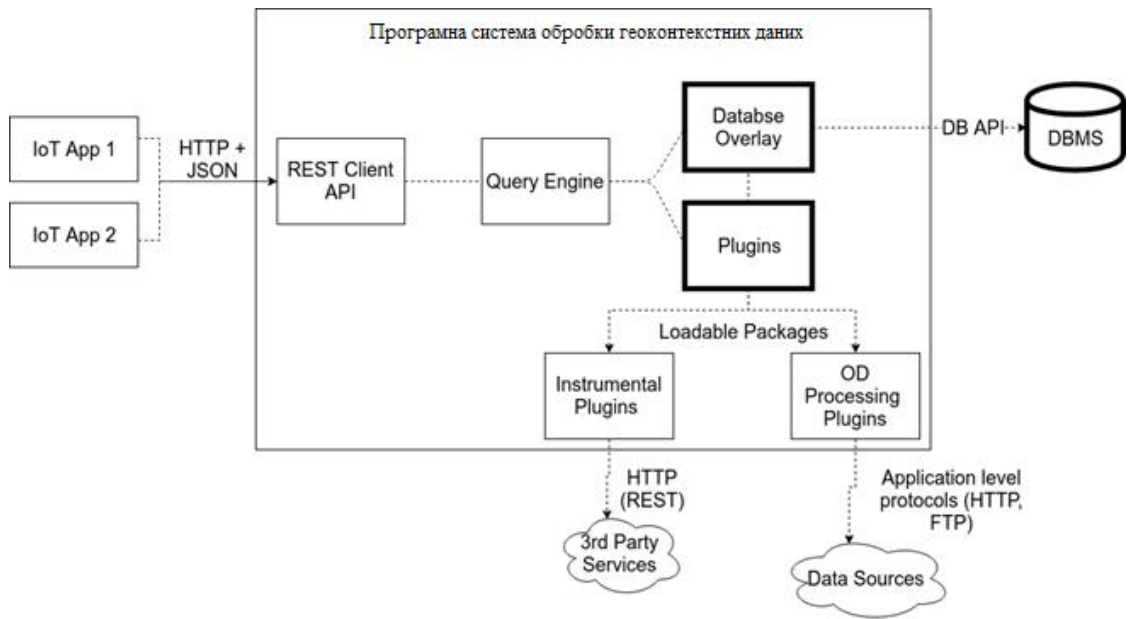
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3.2 –

Database Overlay

HTTP

JSON.

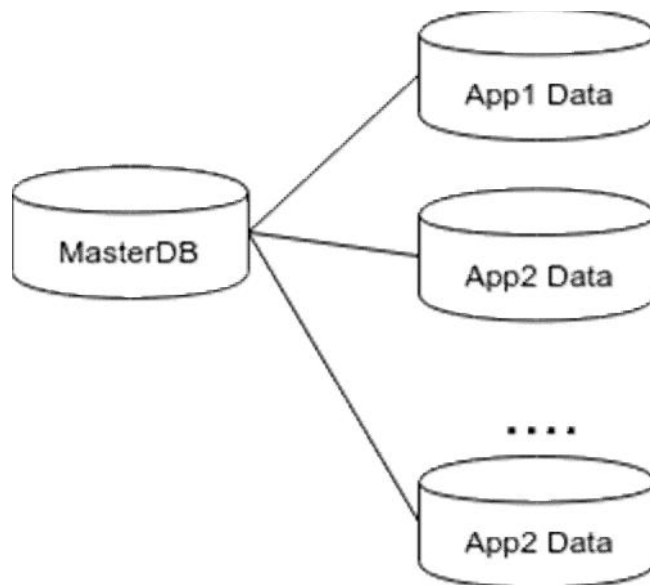
Plugins

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REST-
REST Client API.

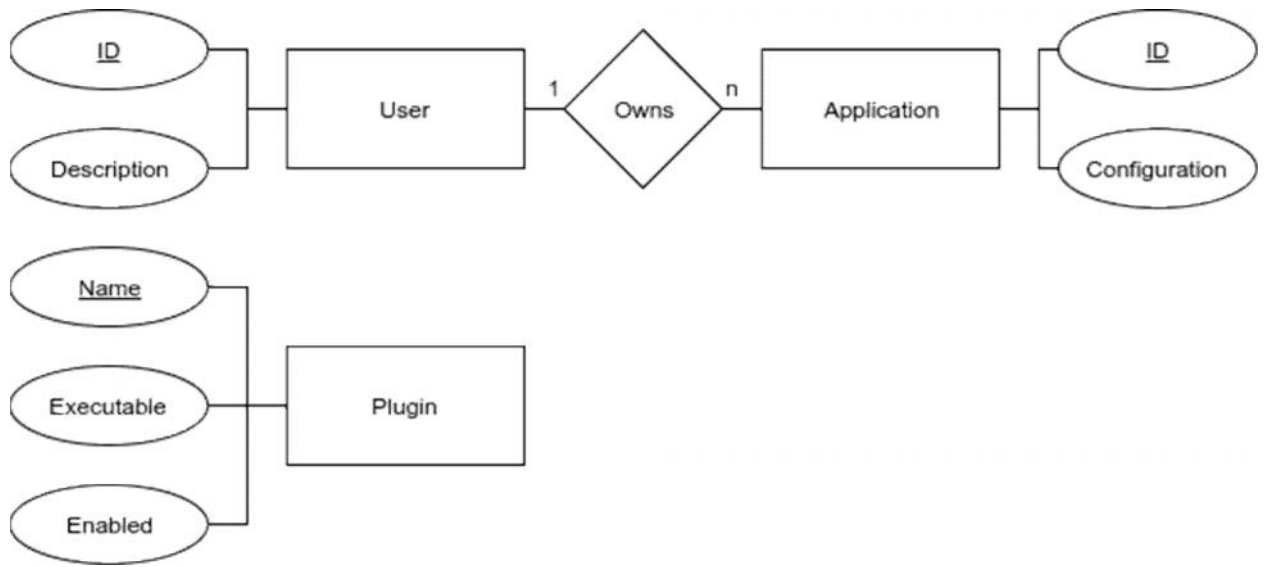
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(3.3).
(MasterDB),



3.3 –

3.4 3.5



3.4 – ER- MasterDB

(3.3).

– User, Plugin Application.

User

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«Channel»

«Description»

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3.3

distance, in intersects

[28].

distance, in

intersects

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3.4

REST « ».

, HTTP-

URL, .

:

- / service / <serviceName>,
- / service / <serviceName> / point,
- / service / <serviceName> / channel,
- / service / <serviceName> / user,
- / plugin /,
-
- plugin / <plugin_name> / service / <serviceName> / job.

, REST- ,

:

- GET – , ;
- PUT – ;
- POST – , ;
- DELETE – .

JSON. GeoJSON.

3.5

OD Processing Plugins

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OD Processing Plugins:

- job – ;
- job_list_resource_factory –
job;
- job_manager – job;
- job_resource – REST- job;
- od_import_parser – ;
- open_data_object_address_getter –
;
- open_data_object_to_point_translator –
Point;
- open_data_objects_loader – ,
- ;
- open_data_objects_parser –
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- open_data_to_points_loader – ,
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- perform_import_actions –
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3.5.1

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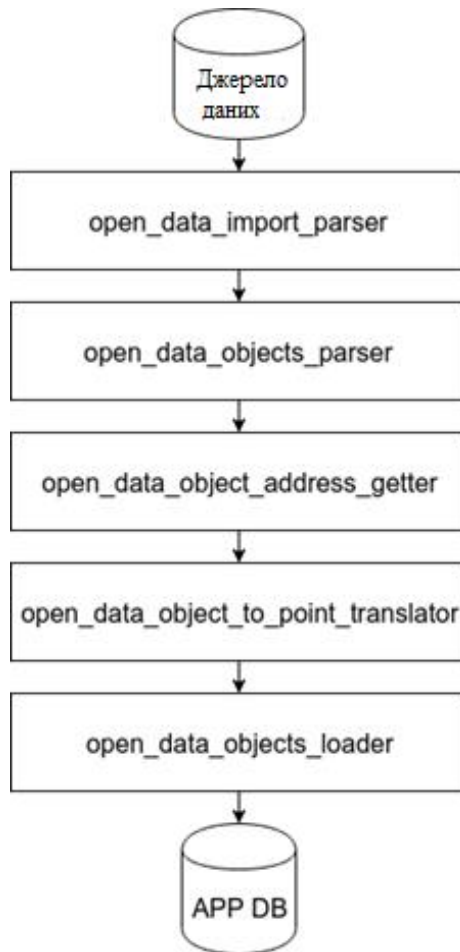
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OD Processing Plugins (3.6):

open_data_import_parser;

open_data_object_address_getter, open_data_object_to_point_translator,
open_data_objects_parser;

open_data_objects_loader thread_job



3.6.

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open_data_objects_loader
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REST-

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geocoder,
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open_data_objects_loader.
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REST-
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3.7

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 LBS- Geo2Tag. ,
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 (Platform as a Service)
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 Geo2Tag Python- Flask,
 MongoDB [22] - Apache.
 REST-

OAuth,

Facebook Google.

Geo2Tag

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MongoDB

MasterDB

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LBS

Geo2Tag.

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Intel (R) Core (TM) i3-2310M CPU @ 2.10GHz

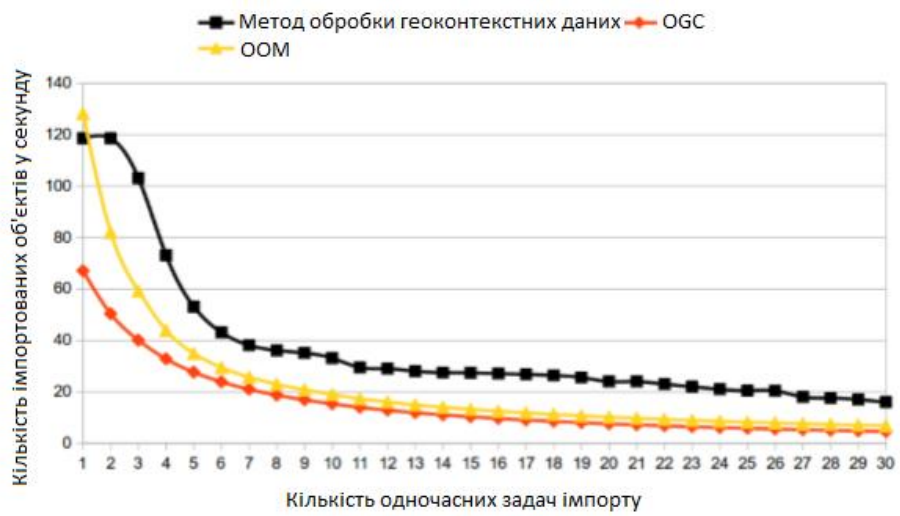
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OGC [10]

3.7.



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Apache,

[68],

Python,

Global Interpreter Lock (GIL)

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6-30,

$$y = -0.9x + 38.0,$$

y -

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3. . – : , 1979. – . 432.
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URL <https://aws.amazon.com/s3/>

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