

## ДОДАТОК А

### Вихідний код розроблених методів

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class LightGCN(MessagePassing):

    def __init__(self):
        super(LightGCN, self).__init__(aggr='add
')

    def update(self, aggr_out, x):

        aggr_out = 0.7*aggr_out + 0.3*x

        return aggr_out

    def message(self, x_j, norm):

        return norm.view(-1, 1) * x_j

    def forward(self, x, edge_index):

        row, col = edge_index
        deg = degree(col)
        deg_inv_sqrt = deg.pow(-0.5)
        norm = deg_inv_sqrt[row] * deg_inv_sqrt[
col]

        return self.propagate(edge_index, x=x, n
orm=norm)

class GNN(torch.nn.Module):

    def __init__(self, embedding_dim, num_nodes,
num_playlists, num_layers):
        super(GNN, self).__init__()

        self.embedding_dim = embedding_dim
        self.num_nodes = num_nodes
        self.num_playlists = num_playlists
        self.num_layers = num_layers

        self.embeddings = torch.nn.Embedding(num

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_embeddings=self.num_nodes, embedding_dim=self.embedding_dim)
        torch.nn.init.normal_(self.embeddings.weight, std=0.1)

        self.layers = torch.nn.ModuleList()
        for _ in range(self.num_layers):
            self.layers.append(LightGCN())

        self.sigmoid = torch.sigmoid

    def forward(self):
        raise NotImplementedError("forward() has not been implemented for the GNN class. Do not use")

    def gnn_propagation(self, edge_index_mp):

        x = self.embeddings.weight

        x_at_each_layer = [x]
        for i in range(self.num_layers):
            x = self.layers[i](x, edge_index_mp)
            x_at_each_layer.append(x)
        final_embs = torch.stack(x_at_each_layer, dim=0).mean(dim=0)
        return final_embs

    def predict_scores(self, edge_index, embs):

        scores = embs[edge_index[0,:], :] * embs[edge_index[1,:], :]
        scores = scores.sum(dim=1)
        scores = self.sigmoid(scores)
        return scores

    def calc_loss(self, data_mp, data_pos, data_neg):

        final_embs = self.gnn_propagation(data_mp.edge_index)

        pos_scores = self.predict_scores(data_pos

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s.edge_index, final_embs)
        neg_scores = self.predict_scores(data_ne
g.edge_index, final_embs)

        loss = -
torch.log(self.sigmoid(pos_scores -
neg_scores)).mean()
        return loss

    def evaluation(self, data_mp, data_pos, k):

        final_embs = self.gnn_propagation(data_m
p.edge_index)

        unique_playlists = torch.unique_consecut
ive(data_pos.edge_index[0,:])
        playlist_emb = final_embs[unique_playlis
ts, :]

        song_emb = final_embs[self.num_playlists
:, :]

        ratings = self.sigmoid(torch.matmul(play
list_emb, song_emb.t()))

        result = recall_at_k(ratings.cpu(), k, s
elf.num_playlists, data_pos.edge_index.cpu(),
                           unique_playlists.cp
u(), data_mp.edge_index.cpu())
        return result

    def recall_at_k(all_ratings, k, num_playlists, g
round_truth, unique_playlists, data_mp):

        known_edges = data_mp[:, data_mp[0,:] < num_p
laylists]

        playlist_to_idx_in_batch = {playlist: i for i
, playlist in enumerate(unique_playlists.tolist())}

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        exclude_playlists, exclude_songs = [], []
        for i in range(known_edges.shape[1]):
            pl, song = known_edges[:,i].tolist()
            if pl in playlist_to_idx_in_batch:
                exclude_playlists.append(playlist_to_idx
x_in_batch[pl])
                exclude_songs.append(song -
num_playlists)
            all_ratings[exclude_playlists, exclude_songs]
            = -10000

        _, top_k = torch.topk(all_ratings, k=k, dim=1
)
        top_k += num_playlists

        ret = {}
        for i, playlist in enumerate(unique_playlists
):
            pos_songs = ground_truth[1, ground_truth[0
, :] == playlist]

            k_recs = top_k[i, :]
            recall = len(np.intersect1d(pos_songs, k_r
ecs)) / len(pos_songs)
            ret[playlist] = recall
        return ret

```

