

## **ДОДАТОК А**

Лістинг програми у Tinkercad

```
#include <Servo.h>

const int waterSensorPin = 2;
const int buzzerPin = 3;
const int ledPin = 4;
const int buttonPin = 5;
const int servoPin = 6;
const int lampPin = 7;

bool alarmTriggered = false;
bool sirenState = false;

unsigned long previousMillis = 0;
const unsigned long interval = 300;

Servo valveServo;

void setup() {
  pinMode(waterSensorPin, INPUT);
  pinMode(buzzerPin, OUTPUT);
  pinMode(ledPin, OUTPUT);
  pinMode(buttonPin, INPUT);
  pinMode(lampPin, OUTPUT);

  valveServo.attach(servoPin);
  valveServo.write(0);

  digitalWrite(lampPin, HIGH);
```

```
Serial.begin(9600);
}

void loop() {
  int water = digitalRead(waterSensorPin);
  int button = digitalRead(buttonPin);

  if (water == HIGH && !alarmTriggered) {
    alarmTriggered = true;
    valveServo.write(90);
    digitalWrite(lampPin, LOW);
    Serial.println("WARNING: Water detected!");
  }

  if (alarmTriggered) {
    unsigned long current = millis();
    if (current - previousMillis >= interval) {
      previousMillis = current;
      sirenState = !sirenState;
      digitalWrite(buzzerPin, sirenState ? HIGH : LOW);
      digitalWrite(ledPin, sirenState ? HIGH : LOW);
    }

    if (button == HIGH) {
      alarmTriggered = false;
      digitalWrite(buzzerPin, LOW);
      digitalWrite(ledPin, LOW);
      valveServo.write(0);
      digitalWrite(lampPin, HIGH);
    }
  }
}
```

```
Serial.println("Alarm stopped.");  
delay(300);  
}  
}  
}
```

**ДОДАТОК Б**

Демонстраційний матеріал

